

● PRINTER RUSH ●

(PTO ASSISTANCE)

JFW

Application : 10/660084 Examiner : McClard GAU : 2837

From : TW Location : IDC FMF FDC Date : 10-8-05

Tracking #: 607973P Week Date: 2-28-05

DOC CODE	DOC DATE	MISCELLANEOUS
<input type="checkbox"/> 1449		<input type="checkbox"/> Continuing Data
<input type="checkbox"/> IDS		<input type="checkbox"/> Foreign Priority
<input checked="" type="checkbox"/> CLM	<u>4-20-05</u>	<input type="checkbox"/> Document Legibility
<input type="checkbox"/> IIFW		<input type="checkbox"/> Fees
<input type="checkbox"/> SRFW		<input type="checkbox"/> Other
<input type="checkbox"/> DRW		
<input type="checkbox"/> OATH		
<input type="checkbox"/> 312		
<input type="checkbox"/> SPEC		

[RUSH] MESSAGE:

Claim 13 in the claim, submitted on 4-20-05 does not end with a period. Is there additional data to be printed or should a claim be entered?

Please verify

Thank You

TW

[XRUSH] RESPONSE: No, there's no need to enter a claim, but I did add a period.

You didn't ask about claim 4: added a period there, also.

INITIALS:

NOTE: This form will be included as part of the official USPTO record, with the Response document coded as XRUSH.

REV 10/04

Appl. No. 10/660,084
Amdt./RCE dated April 18, 2005

3. (Previously added) A control system for a polyphase AC motor having a predetermined horsepower rating, comprising:

two or more integrated AC motor controllers, each integrated controller having a horsepower rating less than the horsepower rating of the AC motor to be controlled, each integrated controller comprising a rectifier section, an inverter section and a controller section;

the rectifier section of each integrated controller being supplied with polyphase AC power;

the inverter section of each integrated controller generating a polyphase, variable frequency, pulse-width-modulated power output; and

a parallel controller communicating with and controlling each integrated controller to thereby control the AC motor.

4. (Previously added) The control system of claim 3, wherein the motor is rated at 800 horsepower or greater.

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5. (Previously added) The control system of claim 3, wherein each integrated controller is rated for 400 horsepower or less.

6. (Previously added) The control system of claim 3, wherein the number of integrated controllers is 3 to 8.

7. (Previously added) The control system of claim 7, further comprising a dynamic brake.

8. (Previously added) The control system of claim 7, wherein the dynamic brake is a chopper circuit.

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9. (Previously added) The control system of claim 7, wherein the dynamic brake is intelligent.
10. (Previously added) The control system of claim 7, wherein the dynamic brake is controlled by the parallel controller.
11. (Previously added) The control system of claim 3, further comprising a conditioning section.
12. (Previously added) A method of controlling an AC motor of predetermined horsepower, comprising:
- providing a plurality of integrated AC motor control systems each having a horsepower rating less than the AC motor to be controlled and each of the integrated control systems comprising a rectifier section, an inverter section and a controller section;
 - supplying polyphase AC power to the rectifier section of each integrated control system;
 - generating a polyphase, variable frequency, pulse-width-modulated power signal from the inverter sections of each integrated control system;
 - interfacing a parallel controller with each integrated control system; and
 - controlling each integrated control system with the parallel controller to thereby control the AC motor.
13. (Previously added) The method of claim 12, wherein the motor is rated at 800 horsepower or greater.
- 12/19/05 14. (Previously added) The method of claim 12, wherein each integrated control system is rated for 400 horsepower or less.
15. (Previously added) The method of claim 12, wherein 3 to 8 integrated control systems are provided.